## Feature

- Microsoft Intelli 3D PS/2 and IBM PS/2 mouse compatible
- Supports rolling buttons in PS/2 mouse mode
- X/Y axis photo input with built-in Holtek's special dynamic photo-input resistor
- Supports three buttons and three axis (X, Y, Z) inputs


## General Description

The HT82M39A is a Plug and Play PS/2 3D mouse controller. It is compatible with Microsoft Intelli 3D PS/2 mouse. The Z axis can

- $Z$ axis can support two kinds of scroller input (optomechanical and mechanical)
- 2 MHz RC oscillator for system frequency with an external pull-high resistor
- 16-pin DIP
support two kinds of scroller input, namely; optomechanical and mechanical.


## Pin Assignment



HT82M39A

## Pin Description

| Pin No. | Pin Name | I/O | Description |
| :---: | :---: | :---: | :---: |
| 1, 2 | Z1, Z2 | I | " Z " axis input supports two kinds of scroller input; optomechanical and mechanical. |
| 3 | VDD | I | Positive power supply pin |
| 4 | NC |  | No connection |
| 5 | VSS | I | Negative power supply pin |
| 6 | OSCI | I | 2 MHz RC oscillator for system frequency with external pull-high resistor and built-in C |
| 7 | CLK | I/O | "CLK I/O": PS/2 mouse CLK line. NMOS open drain output with $5 \mathrm{k} \Omega$ pull-high resistor. |
| 8 | DATA | I/O | "DATA I/O": PS/2 mouse DATA line. NMOS open drain output with $5 \mathrm{k} \Omega$ pull-high resistor. |
| 9~11 | RB, RO, LB | I | Right Button: Normal pull-low ( $50 \mathrm{k} \Omega$ ), <br> Pressing the button connects to high. <br> Rolling Button: Normal pull-low ( $50 \mathrm{k} \Omega$ ), <br> Pressing the button connects to high. <br> Left Button: Normal pull-low ( $50 \mathrm{k} \Omega$ ), <br> Pressing the button connects to high. |
| 12 | TEST | I | For IC manufacture testing, user should leave it floating. |
| 13~16 | X1, X2, Y1, Y2 | I | $\mathrm{X} / \mathrm{Y}$ axis photo input with built-in Holtek's special dynamic photo input resistor |

## Absolute Maximum Ratings



Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

HT82M39A

Electrical Characteristics
$\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Symbol | Parameter | Test Conditions |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathbf{V}_{\text {DD }}$ | Conditions |  |  |  |  |
| $\mathrm{V}_{\mathrm{DD}}$ | Operating Voltage | - | - | 4.5 | 5.0 | 5.5 | V |
| $\mathrm{I}_{\mathrm{OP}}$ | Operating Current | 5 V | $\mathrm{R}_{\mathrm{OSC}}=120 \mathrm{k} \Omega$ | - | - | 15 | mA |
| $\mathrm{f}_{\text {OSC }}$ | RC Oscillator | 5 V | $\mathrm{R}_{\mathrm{OSC}}=120 \mathrm{k} \Omega$ | 1.6 | 2 | 2.2 | V |
| $\mathrm{V}_{\text {IL1 }}$ | Input Low Voltage (Z1, Z2) | 5 V | - | 0 | - | 1.5 | V |
| $\mathrm{V}_{\text {IH1 }}$ | Input High Voltage (Z1, Z2) | 5 V | - | 2.2 | - | 5 | V |
| $\mathrm{V}_{\text {IL2 }}$ | Input Low Voltage (CLK, DATA) | 5 V | - | 0 | - | 0.8 | V |
| $\mathrm{V}_{\mathrm{IH} 2}$ | Input High Voltage (CLK, DATA) | 5 V | - | 2.0 | - | 5.0 | V |
| $\mathrm{R}_{\mathrm{PH} 2}$ | Pull-high Resistor (CLK, DATA) | 5 V | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 2 | 5 | 10 | $\mathrm{k} \Omega$ |
| Isink | Sink Current (CLK, DATA) | 5 V | $\mathrm{V}_{\mathrm{OH}}=0.4 \mathrm{~V}$ | 4 | - | - | mA |
| $\mathrm{V}_{\text {IL3 }}$ | Input Low Voltage (RB, Ro, LB) | 5 V | - | 0 | - | 1.0 | V |
| $\mathrm{V}_{\text {IH3 }}$ | Input High Voltage (RB, Ro, LB) | 5 V | - | 1.8 | - | 5 | V |
| $\mathrm{R}_{\text {PL3 }}$ | Pull-low Resistor (RB, Ro, LB) | 5 V | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 3.0 | 60 | 125 | $\mathrm{k} \Omega$ |
| $\mathrm{V}_{\text {IL4 }}$ | Input Low Voltage (X1, $\mathrm{X} 2, \mathrm{Y} 1, \mathrm{Y} 2)$ | 5 V | - | 0 | - | 1.5 | V |
| $\mathrm{V}_{\text {IH4 }}$ | Input high Voltage (X1, X2, Y1, Y2) | 5 V | - | 2.2 | - | 5 | V |
| $\mathrm{R}_{\text {PL5 }}$ | Dynamic Photo-resistor (X1, X2, Y1, Y2, Z1, Z2) | 5 V | - | See Dynamic resistor characteristics |  |  |  |

## Dynamic resistor characteristics

- R-V curve



## Functional Description

## PS/2 mouse

- PS/2 status byte

Byte 1
bit
7: Reserved
6: $0=$ Stream Mode, $1=$ Remote Mode
5: $0=$ Disabled, $1=$ Enabled
4: $0=$ Scaling $1: 1,1=$ Scaling 2:1
3: $1=$ Wrap Mode, $0=$ Stream or Remote (different from IBM specs.)

2: 1=Left Button Pressed
1: 1=Middle Button Pressed
0: 1=Right Button Pressed
Byte 2
Bit 0~7 current resolution setting
(Bit $0=\mathrm{LSB}$ )
Byte 3
Bit $0 \sim 7$ current sampling rate (Bit $0=\mathrm{LSB}$ )

- Standard PS/2 data format

Variable rps, $0,8,1$, bidirectional, synchronous

| Bit No. | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1st word | YV | XV | YS | XS | 1 | M | R | L |
| 2nd word | X 7 | X 6 | X 5 | X 4 | X 3 | X 2 | X 1 | X 0 |
| 3rd word | Y 7 | Y 6 | Y 5 | Y 4 | Y 3 | Y 2 | Y 1 | Y 0 |

- Data format for 3D PS/2

Variable rps, $0,8,1$, bidirectional, synchronous

| Bit No. | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1st word | YV | XV | YS | XS | 1 | Ro | R | L |
| 2nd word | X 7 | X 6 | X 5 | X 4 | X 3 | X 2 | X 1 | X 0 |
| 3rd word | Y 7 | Y 6 | Y 5 | Y 4 | Y 3 | Y 2 | Y 1 | Y 0 |
| 4th word | Z 7 | Z 6 | Z 5 | Z 4 | Z 3 | Z 2 | Z 1 | Z 0 |

The $\mathrm{x} / \mathrm{y}$ data report is 9 -bit 2 's complement
The z data report is 8 -bit 2 's complement

X movement towards the right is positive, moving towards the left is negative
Y upward movement is positive, moving down is negative
Z rolling towards the user is positive, else negative
Button status: $1=$ pressed, $0=$ released

- Mouse mode changes between Standard and 3D PS/2 mode

Sending the commands in the following sequence will set the mouse to 3D PS/2 mode.

| Command | Response |
| :--- | :--- |
| F3h | FAh |
| C8h | FAh |
| F3h | FAh |
| $64 h$ | FAh |
| F3h | FAh |
| 50h | FAh |
| F2h | FAh, 03h |

- Any time the PC sends a reset "FFh" command to the mouse, it will reset the mouse to Standard PS/2 mode.
- After power-on reset is initiated, the mouse is set to Standard PS/2 mode.


## Timing Diagrams

$\mathrm{X}, \mathrm{Y}$ axis photo-coupler crossed width


X/Y/Z axis counting


## PS/2 mouse

- Data output

(6)

|  | Timing Parameter | Min./Max. |
| :--- | :--- | :--- |
| T1 | DATA transition to the falling edge of CLK | $5 / 25 \mu \mathrm{sec}$ |
| T2 | Rising edge of CLK to DATA transition | $5 / \mathrm{T} 4-5 \mu \mathrm{sec}$ |
| T3 | Inactive CLK Duration | $30 / 50 \mu \mathrm{sec}$ |
| T4 | Active CLK Duration | $30 / 50 \mu \mathrm{sec}$ |
| T5 | Minimum time to inhibit MOUSE after clock 11 | $>0 \mu \mathrm{sec}$ |
| T6 | Maximum time to inhibit MOUSE after clock 11 to ensure | $<50 \mu \mathrm{sec}$ |
|  | MOUSE does not start another transmission |  |

- Data input


|  | Timing Parameter | Min./Max. |
| :--- | :--- | :--- |
| T7 | CLK Duration, low | $30 / 50 \mu \mathrm{sec}$ |
| T8 | CLK Duration, high | $30 / 50 \mu \mathrm{sec}$ |
| T9 | Time from low to high CLK transition to time when <br> MOUSE samples DATA line | $5 / 25 \mu \mathrm{sec}$ |

## Application Circuits

HT82M39A Z axis optomechanical (this application circuit is for reference only)


HT82M39A Z axis optomechanical (this application circuit is for reference only)


HT82M39A Z axis mechanical (this application circuit is for reference only)


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